

# Learning the (other) Code

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- The Arduino Language is a subset of C++
  - C++ and C share many features, so if you only know C, you will still feel at home
- There are Arduino-specific Libraries for extending the Language for specific tasks:
  - Ethernet, WiFi, I2C, SPI, Stepper, Servo, SD, LiquidCrystal, Debounce, FFT,etc

# Learning the (other) Code: Online references

- The Arduino Language reference:
  - <https://www.arduino.cc/en/Reference/HomePage>
- Arduino-specific Libraries:
  - <https://www.arduino.cc/en/Reference/Libraries>
  - Let's take a look at the Libraries (if we have wifi)!

# C++ Beginners' Trap

- C++ is case sensitive
  - `RFpower` is NOT the same as `rfpower` is not the same as `rfPower`
- `camelCase` is usually used for functions and variables
- `PascalCase` is usually used for classes

# Programming – A Few Terms

- **Comment**

- Statement that is used to make a program easier to understand, and which is ignored by the computer

- Comments on a single line start with `//` in C++

- `// This is a comment in C++`

- `int A = 5; //This line contains a comment too!`

- Multi-line comments are bracketed by `/*` and `*/`

- `/* This is what a multi-line comment in C++ looks like */`

# Programming – A Few Terms

- **Variable**

- a memory location paired with an associated symbolic name (an identifier), which contains some known or unknown quantity of information referred to as a value that can be altered during program execution.

- `double myAirspeed = 588.725;`

- **Constant**

- a value that cannot be altered by the program during normal execution

- `const double MyPi = 3.14159;`

# Programming – A Few Terms

- **Data type**

- Specifies the type of value for a variable or constant
  - String
    - “This is a string”
  - char(acter)
    - ‘g’
  - int(eger)
    - 3
  - bool(ean)
    - true false 0 (zero) evaluates to false non-zero evaluates to true
  - double or float (identical on the 8 bit boards; 8 vs 4 byte on Due)
    - 3.78943236593

# Programming – A Few Terms

- Array

- An array is a fixed-size sequential collection of elements of the same data type.

- Ways to declare an array:

- `type arrayName[ arraySize ];`

- `type arrayName[arraySize] = {value, value, value, value};`

- Example:

- `int wattsOut[5] = {10, 20, 30, 40, 50};`

- First element of an array: `arrayName[0];`

- `wattsOut[0] = 10;`

- `wattsOut[3] = 40;`



# Programming – A Few Terms

- **Statement**
  - the smallest standalone element of a programming language that expresses some action to be carried out. In C++, every statement ends with a semi-colon
    - `X = 1;`

# Programming – A Few Terms

- **Function**

- a named section of a program that performs a specific task and returns a value

- `int X (int y)`

- `{`

- `int x = y + 5;`

- `return x;`

- `}`

- “X” would be used in this manner:

- `int A = X(7);`

- Would give A = 12

- Every function has a type and a name; arguments are optional

- A function’s “type” represents the data type that it returns when called

# Programming – A Few Terms

- **Procedure**

- a named section of a program that performs a specific task (such as I/O) but **does not** return a value.

Example:

```
void calcA (int y)
{
  A = y + 5;
}
```

(where “A” is declared elsewhere in the program)

- “calcA” would be used in this manner:

```
int A = 0;
calcA(7);
Serial.print(A);
```

- Would print “12” to the serial port

- **A procedure’s type is always “void”**

- Another example:

```
Serial.begin(9600); ARDUINO OFFICIALLY CALLS THIS A “FUNCTION”; SLOPPY SEMANTICS!!
```

# Programming – A Few Terms

- **Class**

- A type or data structure declared with the keyword class that has data and functions as its members.
- Instances of a class data type are known as **objects**.
- Arduino Class Examples: Serial, String, LiquidCrystal, Stepper, Ethernet, EthernetUDP
- Creating an instance of a class is called **instantiation**
- A class member is accessed using **ClassName.member** syntax

# Programming – A Few Terms

- **Library**

- a collection of precompiled classes containing functions and procedures that a program can use to give it increased functionality
  - Ethernet.h
  - <https://www.arduino.cc/en/Reference/Libraries>

# Ethernet.h

- Library for Ethernet Shield, Ethernet Shield 2, and Leonardo Ethernet. Contains the classes:

**Ethernet:** members `begin()`, `localIP()`, `maintain()`

**IPAddress:** member `IPAddress()`

**Server:** members `Server`, `EthernetServer()`, `begin()`, `available()`, `write()`, `print()`, `println()`

**Client:** members `Client`, `EthernetClient()`, `if(EthernetClient)`, `connected()`, `connect()`, `write()`, `print()`, `println()`, `available()`, `read()`, `flush()`, `stop()`

**EthernetUdp** members `begin()`, `read()`, `write()`, `beginPacket()`, `endPacket()`, `parsePacket()`, `available()`, `stop()`, `remoteIP()`, `remotePort()`

# Programming – A Few Terms

- **Macro**

- A macro is a preprocessing directive defined by the **#define** directive:

- `#define macro_name macro_body`

- e.g.

- `#define X 10`

- Will result in “X” being replaced by “10” everywhere in the code after the `#define` directive

- Both **#define** and **#include** are **preprocessor directives**. They change the source code BEFORE compilation. Other commonly used preprocessor directives include: **#ifndef** and **#endif**

- Preprocessor directives are NOT program statements and they do NOT end with a semicolon.

# Programming – A Few Terms

- **GPIO pin**

- generic pin on an integrated circuit or computer board whose behavior—including whether it is an input or output pin—is controllable by the user at run time

- `GPIO.setup(PIN50, GPIO.OUT);`

- **Analog pin**

- Pin that can read (or sometimes write) analog voltages within a defined range with step size determined by the bit size of the analog-to-digital (read) or digital-to-analog (write) converter

- `pinMode(A0, INPUT);`



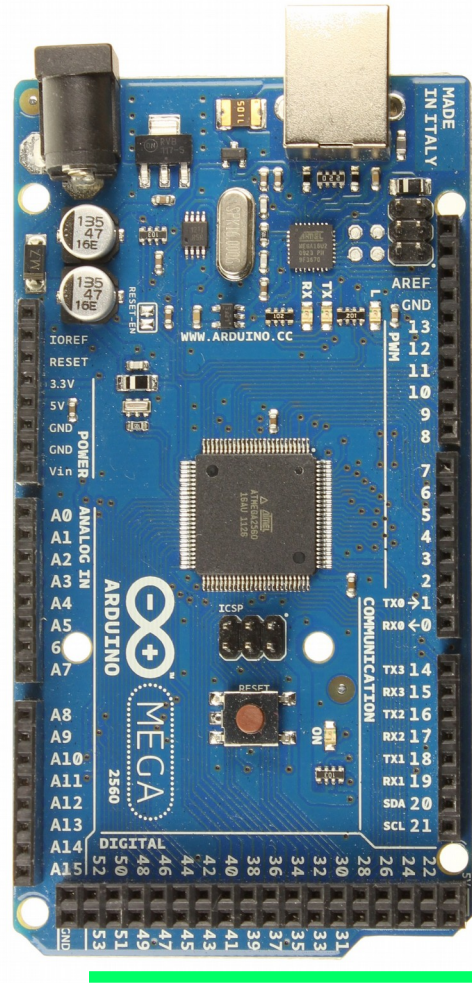
## Inputs:

GPIO Pins

Analog Pins

Serial

Ethernet



## Outputs:

GPIO Pins --> Relays

Analog Pins --> PWM  
motor  
control

Serial --> USB-Serial

Ethernet --> Browser  
Database

# Programming – A Few Terms

- **Operator**

- A symbol that tells the compiler to perform specific mathematical or logical manipulations

- Arithmetic
    - Relational
    - Logical
    - Bitwise
    - Assignment
    - Miscellaneous

# Operators

- Arithmetic
  - + (plus) - (minus) \* (multiply) / (divide) % (modulus, or remainder)
  - ++ (increases integer value by one) -- (decreases integer value by one)
- Relational
  - == (is equal to) != (is not equal to) > (is greater than)
  - < (is less than) >= (is greater than or equal to)
  - <= (is less than or equal to)
- Logical
  - && (and) || (or) ! (not)

# Operators

- Bitwise

**&** (and)   **|** (or)   **^** (exclusive or)   **<<** (shift left)   **>>** (shift right)  
**~** (not)

- Assignment

**=** (equals)

**+=** (adds right operand to the left operand and assigns the result to left operand)

**-=** (subtracts right operand from the left operand and assigns the result to left operand)

**\*=** (multiplies right operand by the left operand and assigns the result to left operand)

**/=** (divides left operand by the right operand and assigns the result to the left operand)

- Miscellaneous

**sizeof()** - returns the size (in bytes) of the argument as integer

**(type)** cast - converts one data type to another (see next slide)

# Cast operator ()

- Cast forces one data type to be converted into another
- Example:

```
double a = 21.123456;
```

```
int c;
```

```
c = (int) a;
```

```
print c;
```

- Will print the result:

```
21
```

# Extra Credit – Bitwise Operator Example

```
/* C Program to demonstrate use of bitwise operators */
#include<stdio.h>
int main()
{
    unsigned char a = 5, b = 9; // a = 5(00000101), b = 9(00001001)
    printf("a = %d, b = %d\n", a, b);
    printf("a&b = %d\n", a&b); // The result is 00000001
    printf("a|b = %d\n", a|b); // The result is 00001101
    printf("a^b = %d\n", a^b); // The result is 00001100
    printf("~a = %d\n", a = ~a); // The result is 11111010
    printf("b<<1 = %d\n", b<<1); // The result is 00010010
    printf("b>>1 = %d\n", b>>1); // The result is 00000100
    return 0;
}
```

From: <https://www.geeksforgeeks.org/interesting-facts-bitwise-operators-c/>

Output:

a = 5, b = 9

a&b = 1

a|b = 13

a^b = 12

~a = 250

b<<1 = 18

b>>1 = 4

# Programming – A Few Terms

- **Decision Statement**

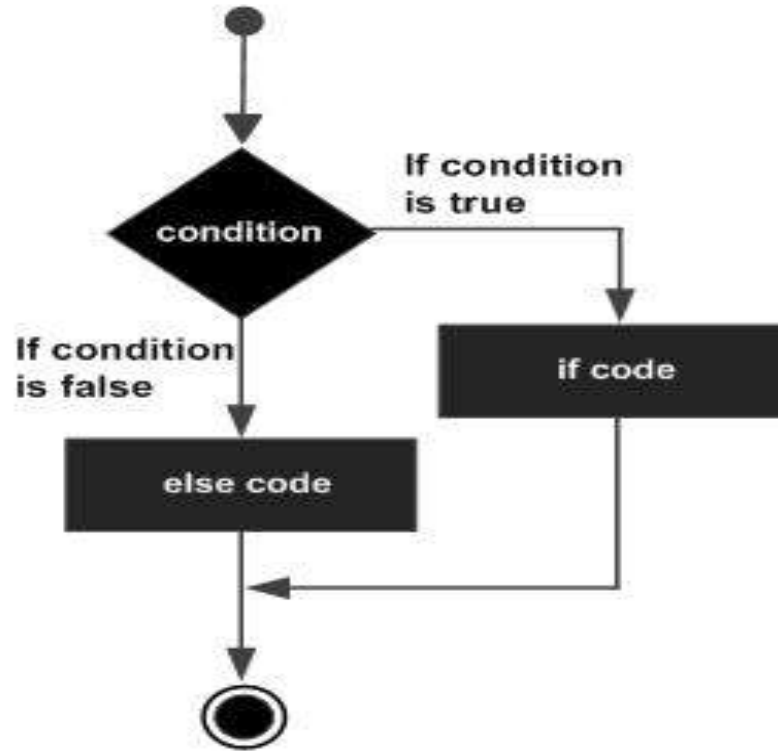
- Statement that causes various courses of action to be taken depending on certain conditions (a form of “flow control”)

- **if, else if, else**

- if
- if...else
- if...else if
- if...else if...else
- if...else if...else if
- if...else if...else if...else etc.

- **switch**

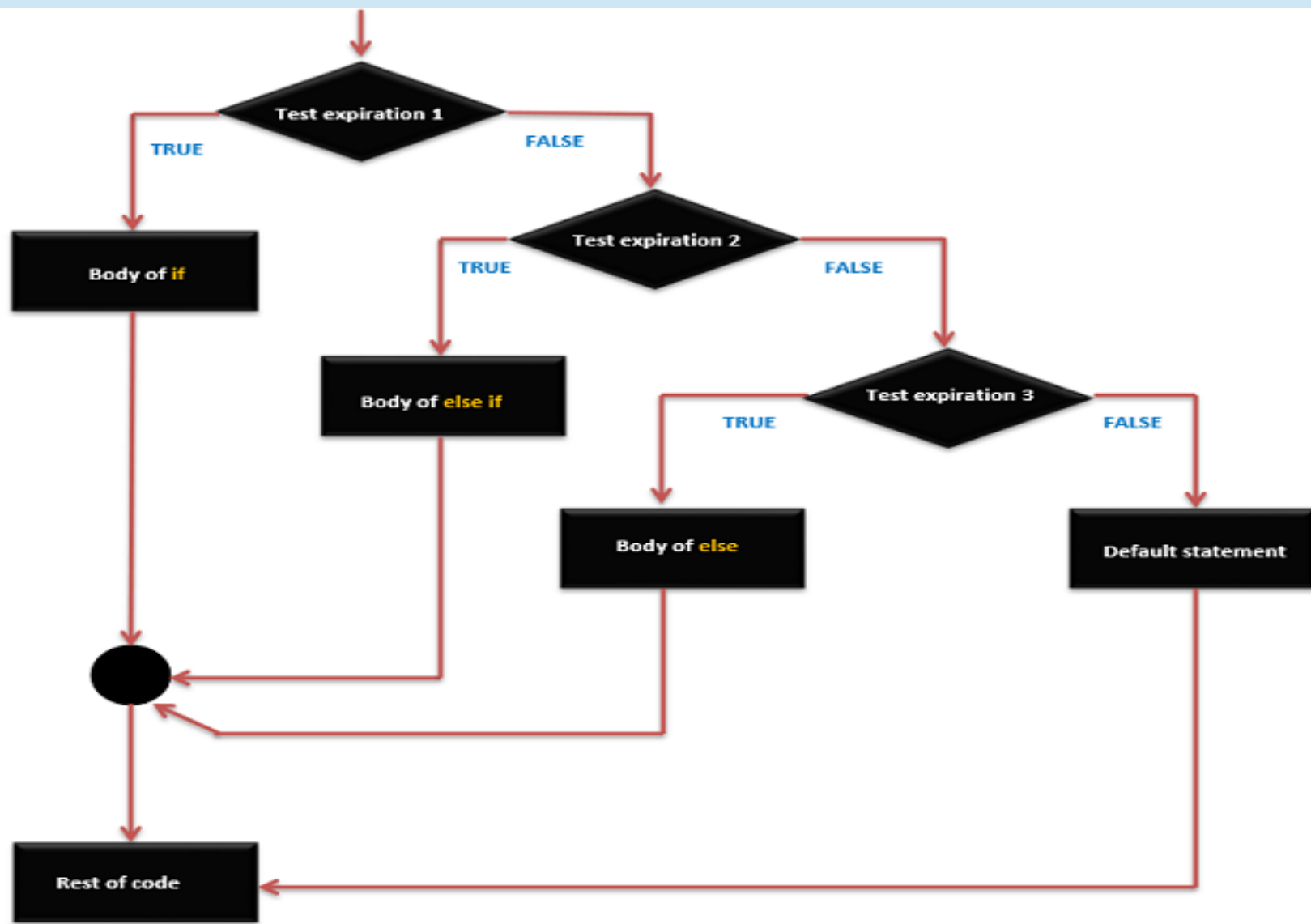
# if/else Statement



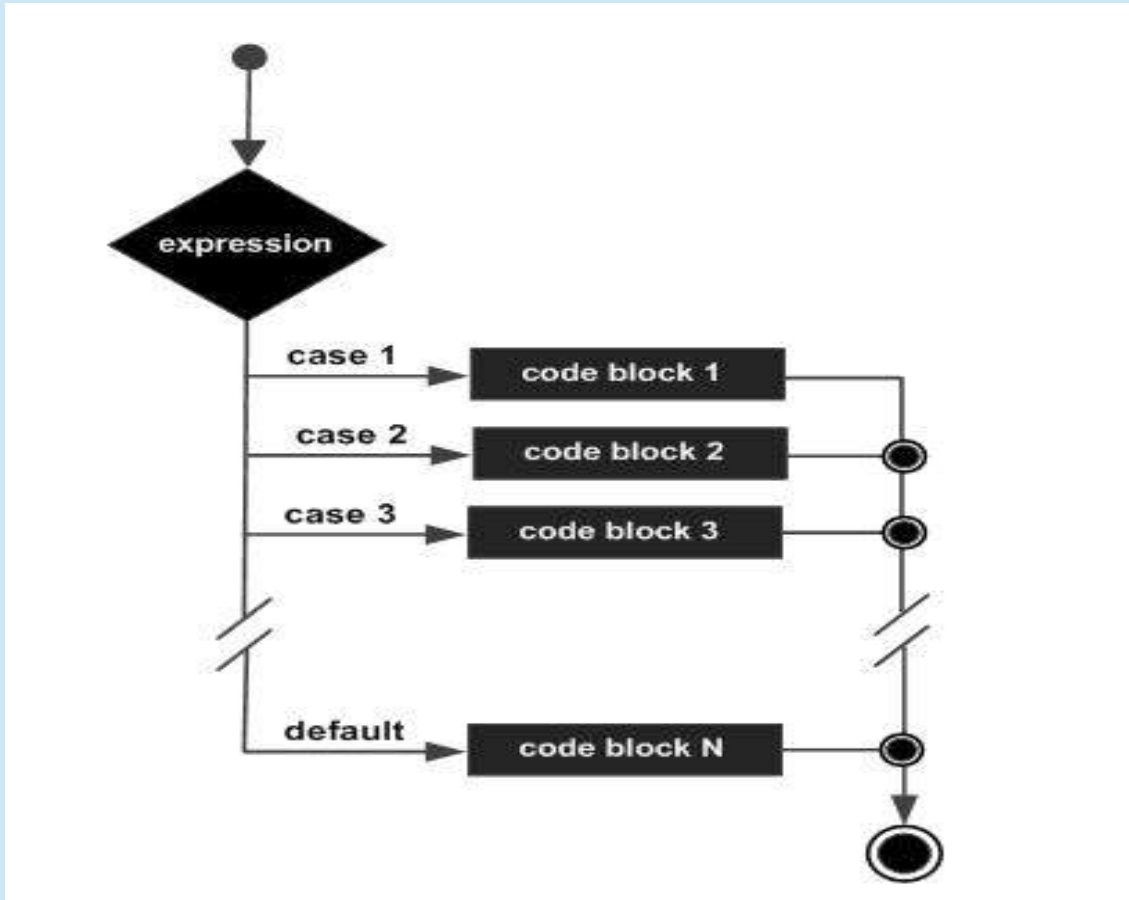


# if / else if / else Example

```
if (band == 50)
    {relay50Pin = On;
    relay144Pin = Off;}
else if (band ==144)
    {relay50Pin = Off;
    relay144Pin = On;}
else
    {relay50Pin = Off;
    relay144Pin = Off;}
```



switch : an alternative to  
if / else if / else if / else if .... / else



**FOR  
INTEGRAL and  
ENUMERATED  
TYPES ONLY  
e.g. integers,  
characters,  
booleans**

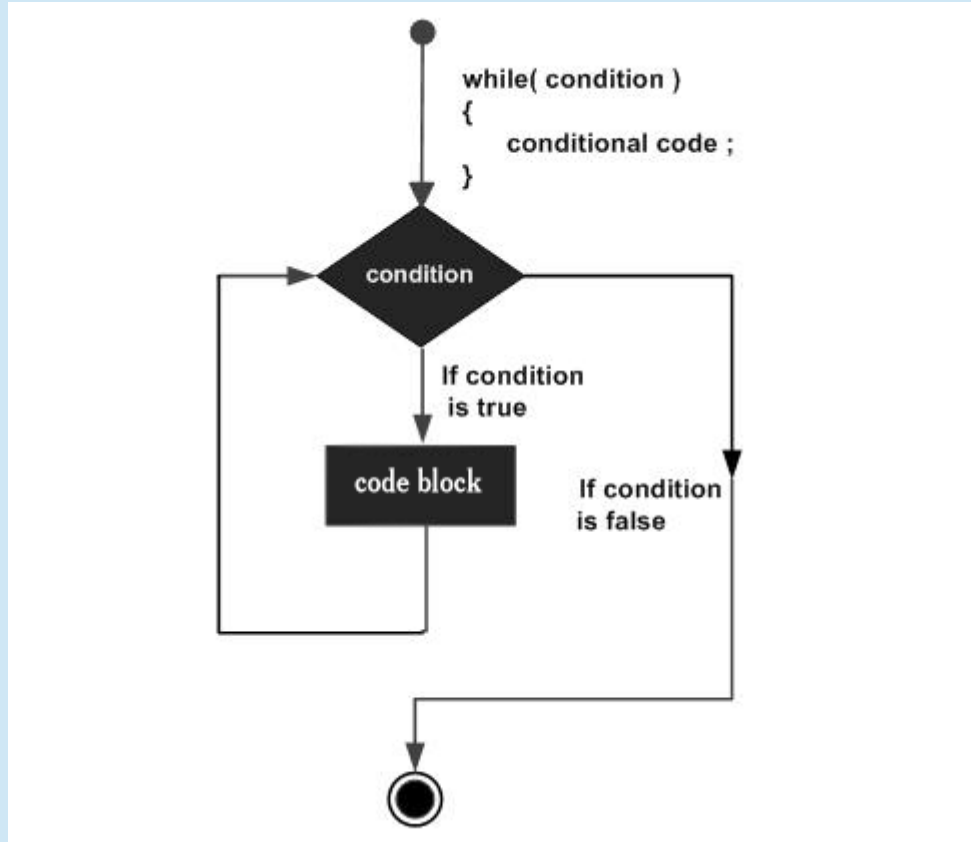
# Switch Example

```
switch (band){  
  case 50: {  
    relay50Pin = On;  
    relay144Pin = Off;  
    break; }  
  case 144: {  
    relay50Pin = Off;  
    relay144Pin = On;  
    break; }  
  default: {  
    relay50Pin = Off;  
    relay144Pin = Off; }}}
```

# Another Form of Flow Control

## ”while” Loop

```
while(condition){  
statements  
}
```



```
while(condition){  
statements  
}
```

```
var=0;  
while(var < 200){  
var++;  
print var;  
}
```



Prints integers from 1 to 200

# Another form of flow control the “for” loop

- Used for code that needs to execute repetitively:

```
for(init; condition; increment) {  
    statements; }  
}
```

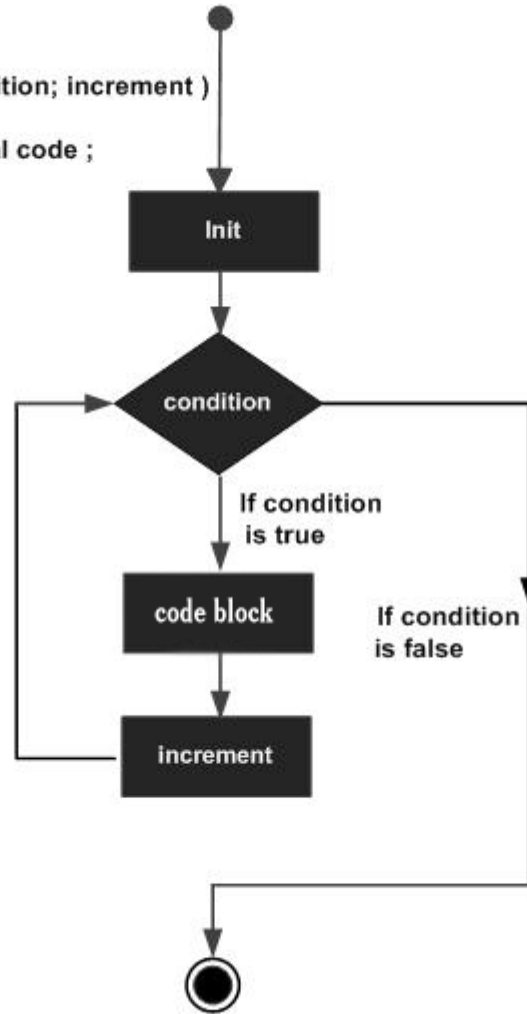
init step is executed first, and only once

condition evaluated; if true, statements in the body of the loop are executed. If false, body of loop is not executed and control jumps to next statement after the loop

after the body of the loop executes, flow of control jumps to increment statement and increment is performed

condition is again evaluated. When condition is false, loop terminates

```
for( init; condition; increment )  
{  
  conditional code ;  
}
```



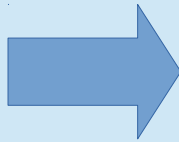


# “for” loop: example

- Used for code that needs to execute repetitively:

```
for(init; condition; increment) {  
    statements; }  
}
```

```
for(i=0; i<4; i++) {  
    print i; }  
}
```



Output:

0  
1  
2  
3


# Curly braces

{ }


- Are used to group a set of statements; always come in pairs
- Be careful with them; misplaced curly braces are a major source of bugs!

# Curly brace madness

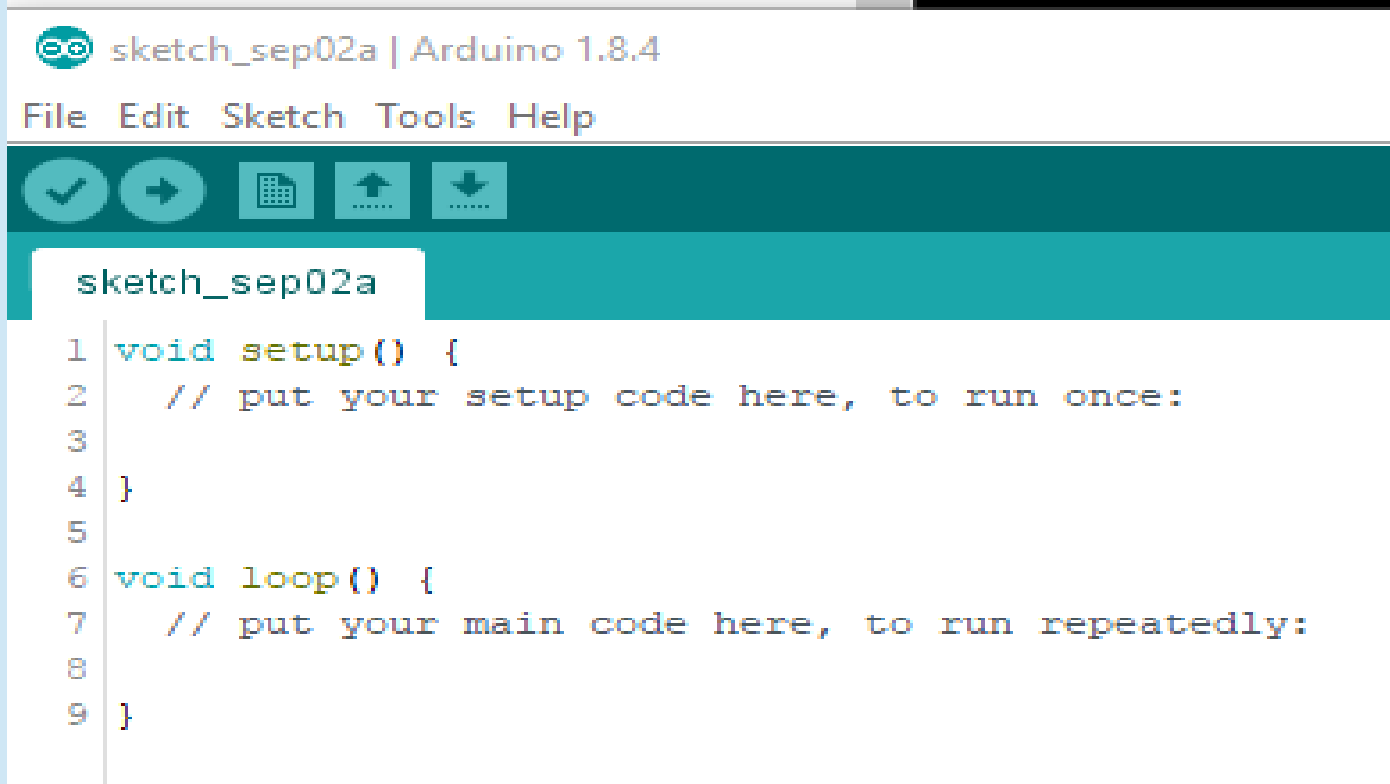
```
if (band == 50)
{relay50Pin = On;
relay144Pin = Off;}
else if (band ==144)
{relay50Pin = Off;
relay144Pin = On;}
else
{relay50Pin = Off;
relay144Pin = Off;}
```

  
Correct

```
if (band == 50)
{relay50Pin = On;
relay144Pin = Off;}
else if (band ==144)
{relay50Pin = Off;
relay144Pin = On;}
else
{relay50Pin = Off;}
relay144Pin = Off;
```

 Incorrect

# Programming Steps – Getting Started



The image shows a screenshot of the Arduino IDE interface. At the top, the window title is "sketch\_sep02a | Arduino 1.8.4". Below the title bar is a menu bar with "File", "Edit", "Sketch", "Tools", and "Help". Underneath the menu bar is a toolbar with five icons: a checkmark, a right-pointing arrow, a grid, an up arrow, and a down arrow. The main workspace shows a tab labeled "sketch\_sep02a" containing the following code:

```
1 void setup() {  
2   // put your setup code here, to run once:  
3  
4 }  
5  
6 void loop() {  
7   // put your main code here, to run repeatedly:  
8  
9 }
```

# Programming Steps - General

1) Include libraries containing classes with external functions (Optional)

2) Define variables and constants (Optional)

3) Setup ()

Define and initialize GPIO pins / Analog I/O pins

Define, start, serial port(s), Ethernet port(s)

4) Loop()

Receive input from ports / GPIO pins / Analog pins

Parse / process data to extract desired information

Use information derived from data to perform desired task (e.g. switch GPIO pins) or to send information to client computer

5) From within Loop(), call other functions() as needed (Optional)

# A Simple Program

## Blink

File Edit Sketch Tools Help

- New Ctrl+N
- Open... Ctrl+O
- Open Recent >
- Sketchbook >
- Examples** >
- Close Ctrl+W
- Save Ctrl+S
- Save As... Ctrl+Shift+S
- Page Setup Ctrl+Shift+P
- Print Ctrl+P
- Preferences Ctrl+Comma
- Quit Ctrl+Q

Built-in Examples

- 01.Basics** >
- 02.Digital >
- 03.Analog >
- 04.Communication >
- 05.Control >
- 06.Sensors >
- 07.Display >
- 08.Strings >
- 09.USB >
- 10.StarterKit\_BasicKit >
- 11.ArduinoISP >

Examples for any board

- Adafruit Circuit Playground >
- Bridge >
- Esplora >
- Ethernet >
- Firmata >
- GSM >
- LiquidCrystal >
- Robot Control >
- Robot Motor >
- SD >
- Servo >
- SpacebrewYun >
- Stepper >
- Temboo >
- TFT >
- WiFi >
- RETIRED >

Examples for Arduino/Genuino Uno

- EEPROM >
- SoftwareSerial >
- SPI >
- Wire >

- AnalogReadSerial
- BareMinimum
- Blink**
- DigitalReadSerial
- Fade
- ReadAnalogVoltage

```

15 //define constant pin
16 const int Pin50 = 2; //
17 const int Pin144 = 3;
18 const int Pin222 = 4;
19 const int Pin432 = 5;
20 const int Pin902 = 6;
21 const int Pin1296 = 8;
22 const int Pin2304 = A5
23 const int Pin3G = A4;
24 const int Pin5G = A3;
25 const int Pin10G = A2;
26 const int Pin24G = A1;
27 const int Pin47G = A0;
28 const int Pin76G = 7;
29
30 void setup() {
31
32 // define GPIO pins as
33 pinMode(Pin50, OUTPUT);
34 pinMode(Pin144, OUTPUT);
35 pinMode(Pin222, OUTPUT);
36 pinMode(Pin432, OUTPUT);
37 pinMode(Pin902, OUTPUT);
38 pinMode(Pin1296, OUTPUT);
39 pinMode(Pin2304, OUTPUT);
40 pinMode(Pin3G, OUTPUT);
41 pinMode(Pin5G, OUTPUT);
42 pinMode(Pin10G, OUTPUT);
43 pinMode(Pin24G, OUTPUT);
44 pinMode(Pin47G, OUTPUT);
45 pinMode(Pin76G, OUTPUT);
46
47 //initialize all GPIO
    
```

converter bandswitch.  
 ing data  
 lete

```
1 /*
2  Blink
3
4  Turns an LED on for one second, then off for one second, repeatedly.
5
6  Most Arduinos have an on-board LED you can control. On the UNO, MEGA and ZERO
7  it is attached to digital pin 13, on MKR1000 on pin 6. LED_BUILTIN is set to
8  the correct LED pin independent of which board is used.
9  If you want to know what pin the on-board LED is connected to on your Arduino
10 model, check the Technical Specs of your board at:
11 https://www.arduino.cc/en/Main/Products
12
13 modified 8 May 2014
14 by Scott Fitzgerald
15 modified 2 Sep 2016
16 by Arturo Guadalupi
17 modified 8 Sep 2016
18 by Colby Newman
19
20 This example code is in the public domain.
21
22 http://www.arduino.cc/en/Tutorial/Blink
23 */
24
```



```
25 // the setup function runs once when you press reset or power the board
26 void setup() {
27   // initialize digital pin LED_BUILTIN as an output.
28   pinMode(LED_BUILTIN, OUTPUT);
29 }
30
31 // the loop function runs over and over again forever
32 void loop() {
33   digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the voltage level)
34   delay(1000); // wait for a second
35   digitalWrite(LED_BUILTIN, LOW); // turn the LED off by making the voltage LOW
36   delay(1000); // wait for a second
37 }
```

# A Simple Program

## Live Demo

### Blink

# HOW TO WRITE GOOD CODE:

